NAG Toolbox for MATLAB

f07vh

1 Purpose

f07vh returns error bounds for the solution of a real triangular band system of linear equations with multiple right-hand sides, AX = B or $A^{T}X = B$.

2 Syntax

```
[ferr, berr, info] = f07vh(uplo, trans, diag, kd, ab, b, x, 'n', n, 'nrhs_p', nrhs_p)
```

3 Description

f07vh returns the backward errors and estimated bounds on the forward errors for the solution of a real triangular band system of linear equations with multiple right-hand sides AX = B or $A^{T}X = B$. The function handles each right-hand side vector (stored as a column of the matrix B) independently, so we describe the function of f07vh in terms of a single right-hand side b and solution x.

Given a computed solution x, the function computes the *component-wise backward error* β . This is the size of the smallest relative perturbation in each element of A and b such that x is the exact solution of a perturbed system

$$|\delta a_{ij}| \le \beta |a_{ij}|$$
 $(A + \delta A)x = b + \delta b$
and $|\delta b_i| \le \beta |b_i|$.

Then the function estimates a bound for the *component-wise forward error* in the computed solution, defined by:

$$\max_{i}|x_{i}-\hat{x}_{i}|/\max_{i}|x_{i}|$$

where \hat{x} is the true solution.

For details of the method, see the F07 Chapter Introduction.

4 References

Golub G H and Van Loan C F 1996 Matrix Computations (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

5.1 Compulsory Input Parameters

1: **uplo – string**

Indicates whether A is upper or lower triangular.

uplo = 'U'

A is upper triangular.

uplo = 'L'

A is lower triangular.

Constraint: uplo = 'U' or 'L'.

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2: trans – string

Indicates the form of the equations.

$$trans = 'N'$$

The equations are of the form AX = B.

$$trans = 'T' or 'C'$$

The equations are of the form $A^{\mathrm{T}}X = B$.

Constraint: trans = 'N', 'T' or 'C'.

3: **diag – string**

Indicates whether A is a nonunit or unit triangular matrix.

$$diag = 'N'$$

A is a nonunit triangular matrix.

$$diag = 'U'$$

A is a unit triangular matrix; the diagonal elements are not referenced and are assumed to be 1.

Constraint: diag = 'N' or 'U'.

4: kd – int32 scalar

 k_d , the number of superdiagonals of the matrix A if **uplo** = 'U', or the number of subdiagonals if **uplo** = 'L'.

Constraint: $\mathbf{kd} \geq 0$.

5: ab(ldab,*) - double array

The first dimension of the array ab must be at least kd + 1

The second dimension of the array must be at least $max(1, \mathbf{n})$

The n by n triangular band matrix A.

The matrix is stored in rows 1 to $k_d + 1$, more precisely,

if **uplo** = 'U', the elements of the upper triangle of A within the band must be stored with element A_{ii} in $\mathbf{ab}(k_d+1+i-j,j)$ for $\max(1j-k_d) \le i \le j$;

if **uplo** = 'L', the elements of the lower triangle of A within the band must be stored with element A_{ij} in $\mathbf{ab}(1+i-j,j)$ for $j \le i \le \min(nj+k_d)$.

If diag = 'U', the diagonal elements of A are assumed to be 1, and are not referenced.

6: b(ldb,*) - double array

The first dimension of the array **b** must be at least $max(1, \mathbf{n})$

The second dimension of the array must be at least max(1, nrhs_p)

The n by r right-hand side matrix B.

7: $\mathbf{x}(\mathbf{ldx},*) - \mathbf{double} \ \mathbf{array}$

The first dimension of the array \mathbf{x} must be at least $\max(1, \mathbf{n})$

The second dimension of the array must be at least max(1, nrhs p)

The n by r solution matrix X, as returned by f07ve.

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5.2 Optional Input Parameters

1: n - int32 scalar

Default: The second dimension of the array ab.

n, the order of the matrix A.

Constraint: $\mathbf{n} \geq 0$.

2: nrhs p - int32 scalar

Default: The second dimension of the array **b** The second dimension of the array \mathbf{x} .

r, the number of right-hand sides.

Constraint: $\mathbf{nrhs}_{\mathbf{p}} \geq 0$.

5.3 Input Parameters Omitted from the MATLAB Interface

ldab, ldb, ldx, work, iwork

5.4 Output Parameters

1: ferr(*) - double array

Note: the dimension of the array **ferr** must be at least $max(1, nrhs_p)$.

ferr(j) contains an estimated error bound for the jth solution vector, that is, the jth column of X, for j = 1, 2, ..., r.

2: berr(*) - double array

Note: the dimension of the array **berr** must be at least $max(1, nrhs_p)$.

berr(j) contains the component-wise backward error bound β for the jth solution vector, that is, the jth column of X, for j = 1, 2, ..., r.

3: info - int32 scalar

info = 0 unless the function detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the function:

```
info = -i
```

If info = -i, parameter i had an illegal value on entry. The parameters are numbered as follows:

1: uplo, 2: trans, 3: diag, 4: n, 5: kd, 6: nrhs_p, 7: ab, 8: ldab, 9: b, 10: ldb, 11: x, 12: ldx, 13: ferr, 14: berr, 15: work, 16: iwork, 17: info.

It is possible that **info** refers to a parameter that is omitted from the MATLAB interface. This usually indicates that an error in one of the other input parameters has caused an incorrect value to be inferred.

7 Accuracy

The bounds returned in **ferr** are not rigorous, because they are estimated, not computed exactly; but in practice they almost always overestimate the actual error.

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8 Further Comments

A call to f07vh, for each right-hand side, involves solving a number of systems of linear equations of the form Ax = b or $A^{T}x = b$; the number is usually 4 or 5 and never more than 11. Each solution involves approximately 2nk floating-point operations (assuming $n \gg k$).

The complex analogue of this function is f07vv.

9 Example

```
uplo = 'L';
trans = 'N';
diag = 'N';
kd = int32(1);
ab = [-4.16, 4.78, 6.32, 0.16;
-2.25, 5.86, -4.82, 0];
b = [-16.64, -4.16;
-13.78, -16.59;
     13.1, -4.94;
     -14.14, -9.960000000000001];
x = [4, 1;
     -0.99999999999998, -3;
     3, 2;
1.99999999999988, -2.000000000000002];
[ferr, berr, info] = f07vh(uplo, trans, diag, kd, ab, b, x)
ferr =
   1.0e-13 *
    0.5716
    0.5829
berr =
   1.0e-16 *
    0.6142
    0.2526
info =
            0
```

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